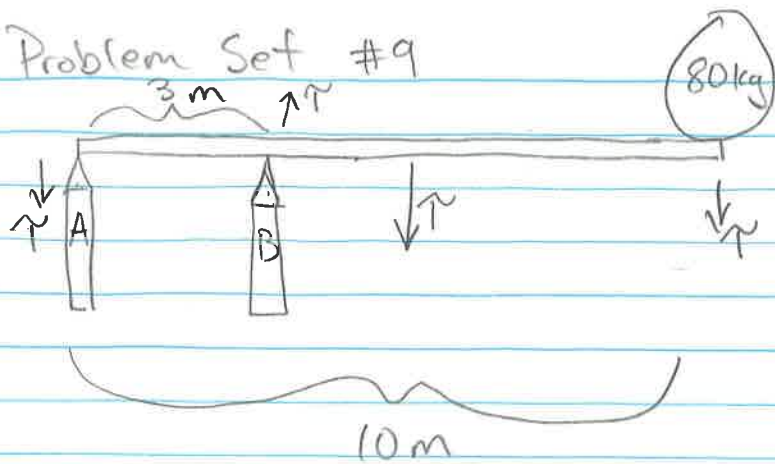


Problem Set #9

✓ 1)



a) "A is pivot point"

$$\sum \uparrow = 0$$

$$(80 \text{ kg}) (10 \frac{\text{m}}{s^2}) (10 \text{ m}) = (F_B) (3 \text{ m})$$

$$F_B = 2667 \text{ N } \uparrow \text{ upwards}$$

"B" is pivot point

$$\sum \uparrow = 0$$

$$-(80 \text{ kg}) (10 \frac{\text{m}}{s^2}) (7 \text{ m}) = (F_A) (3 \text{ m})$$

$$F_A = 1867 \text{ N } \downarrow \text{ downwards}$$

b) $m_{\text{board}} = 100 \text{ kg}$

"A is pivot", $\sum \uparrow = 0$

$$(80 \text{ kg}) (10 \frac{\text{m}}{s^2}) (10 \text{ m}) + (100 \text{ kg}) (10 \frac{\text{m}}{s^2}) (5 \text{ m}) = (F_B) (3 \text{ m})$$

$$F_B = 4333.3 \text{ N } \uparrow \text{ up}$$

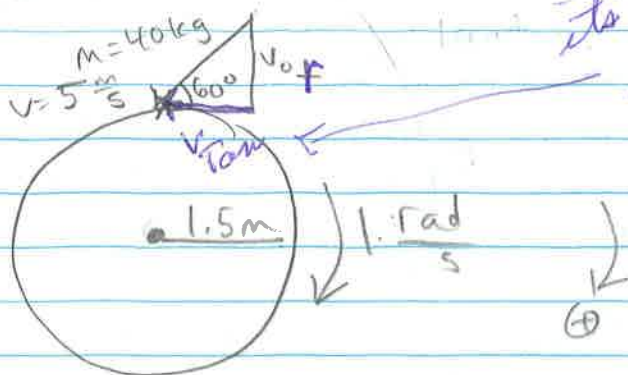
"B is pivot", $\sum \uparrow = 0$

$$(F_A) (3 \text{ m}) = (100 \text{ kg}) (10 \frac{\text{m}}{s^2}) (2 \text{ m}) + (80 \text{ kg}) (10 \frac{\text{m}}{s^2}) (7 \text{ m})$$

$$F_A = 2533.3 \text{ N } \downarrow \text{ down}$$

Problem Set #9

✓ 2)



$M = 100 \text{ kg}$
its tangential velocity we need

a) conservation of angular momentum

$$l_{oc} = \frac{1}{2}(100 \text{ kg})(1.5 \text{ m})^2 (1 \frac{\text{rad}}{\text{s}})$$

$$* l_{\text{carousel}} = 112.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}}$$

$$l_{\text{kid}} = (40 \text{ kg})(1.5 \text{ m})^2 \left(\frac{(\cos 60)(-5 \frac{\text{m}}{\text{s}})}{1.5 \text{ m}} \right)$$

$$l_{\text{kid}} = -150 \frac{\text{kg} \cdot \text{m}^2}{\text{s}}$$

$$l_{oc} + l_{ok} = l_{\text{final}}$$

$$112.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} - 150 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = -37.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = l_{\text{final}}$$

(counterclockwise)

$$-37.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = (I_k + I_c)(\omega_f)$$

$$-37.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = \left(\frac{1}{2}(100 \text{ kg})(1.5^2) + (40 \text{ kg})(1.5^2) \right) (\omega_f)$$

$$\omega_f = -0.19 \frac{\text{radians}}{\text{sec}} \quad \odot$$

b) $l_{oc} = -112.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}}$ (counterclockwise), $l_{ok} = -150 \frac{\text{kg} \cdot \text{m}^2}{\text{s}}$ (c-clockwise)

$$l_{oc} + l_{ok} = l_f$$

$$-112.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} - 150 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = -262.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = l_f$$

$$-262.5 \frac{\text{kg} \cdot \text{m}^2}{\text{s}} = \left(\frac{1}{2}(100 \text{ kg})(1.5^2) + (40 \text{ kg})(1.5^2) \right) (\omega_f)$$

$$\omega_f = 1.3 \frac{\text{radians}}{\text{s}} \quad \odot$$

* This is for part a

$$c) KE = \frac{1}{2} I \omega^2$$

$$KE_k = \frac{1}{2} ((40 \text{ kg})(1.5 \text{ m}^2)) \left(\frac{(\cos 60)(5 \text{ m/s})}{1.5 \text{ m}} \right)^2$$

$$* KE_k = 125 \text{ J}$$

$$KE_c = \frac{1}{2} \left(\frac{1}{2} (100 \text{ kg})(1.5^2) \right) \left(1 \frac{\text{rad}}{\text{s}} \right)^2$$

$$* KE_c = 56.25 \text{ J}, \quad KE_{\text{total}} = 181.25 \text{ J}$$

$$KE_{(k+c)} = \frac{1}{2} ((40 \text{ kg})(1.5 \text{ m}^2) + \frac{1}{2} (100 \text{ kg})(1.5 \text{ m}^2)) \left(0.19 \frac{\text{rad}}{\text{s}} \right)^2$$

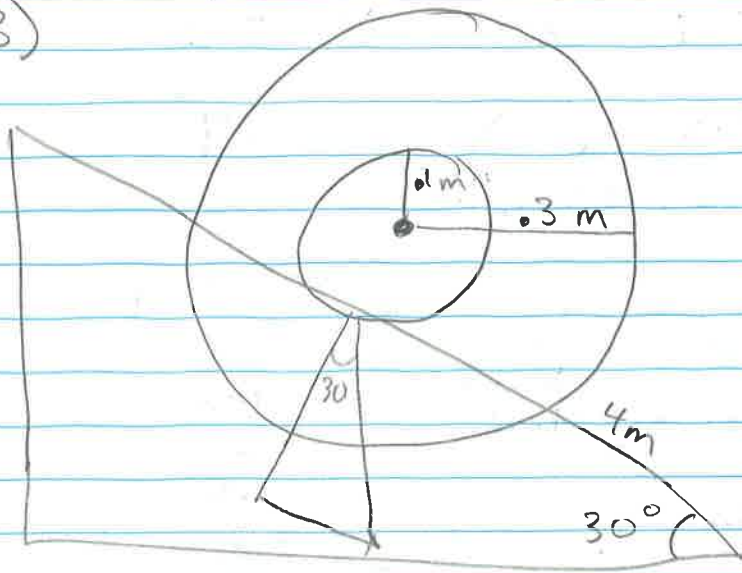
$$KE_{(k+c_f)} = 19.24 \text{ J}, \quad KE \text{ is not conserved}$$

* KE is not conserved b/c energy is lost through heat

Problem Set #9

→ 3)

$$M = 3 \text{ kg}$$



a) $PE_{\text{lost}} = KE_{\text{gained}}$
 $KE = I\omega^2$, $I = \frac{1}{2}mr^2$
 $PE_{\text{lost}} = PE_0 - PE_f$
 $PE_{\text{lost}} = (3 \text{ kg})(10 \frac{\text{m}}{\text{s}})(\sin 30)(4 \text{ m}) - 0$

$$PE_{\text{lost}} = 60 \text{ J}$$

b) $\Delta PE = \Delta KE_{\text{rot}} + \Delta KE_{\text{trans}}$ $\omega = \frac{v}{r}$
 $60 \text{ J} = \frac{1}{2}I\omega^2 + \frac{1}{2}mv^2$

$$60 \text{ J} = \frac{1}{2} \left(\frac{1}{2} (3 \text{ kg}) (.3 \text{ m})^2 \right) \left(\frac{v}{.1 \text{ m}} \right)^2 + \frac{1}{2} (3 \text{ kg}) v^2$$

$$60 \text{ J} = (6.75) (v^2) + (1.5) (v^2)$$

$$(7.27 \frac{\text{m}^2}{\text{s}^2}) = v^2$$

$$v_f = 2.7 \frac{\text{m}}{\text{s}}$$

$$v = (\omega)(r)$$

$$\left(\frac{2.7 \frac{\text{m}}{\text{s}}}{.1 \text{ m}} \right) = \omega$$

$$\omega_f = 27 \frac{\text{radians}}{\text{s}}$$

c) $\text{avg vel} = \frac{(2.7 \frac{\text{m}}{\text{s}}) + (0 \frac{\text{m}}{\text{s}})}{2} = \text{avg vel} = 1.35 \frac{\text{m}}{\text{s}}$

$$v = \frac{m}{t}, 1.35 \frac{\text{m}}{\text{s}} = \frac{(4 \text{ m})}{(t)} \quad t = 2.96 \text{ s}$$

$$\text{lin. accel} = \frac{\Delta v}{\Delta t} = \frac{2.7 \frac{\text{m}}{\text{s}}}{2.96} = \text{lin. accel} = .91 \frac{\text{m}}{\text{s}^2} \quad \alpha = \frac{\Delta \omega}{\Delta t} = \frac{27 \frac{\text{rad}}{\text{s}}}{2.96 \text{ s}} \quad \alpha = 9.12 \frac{\text{rad}}{\text{s}^2}$$

$$d) \alpha = 9.12 \frac{\text{rad}}{\text{s}^2}, \tau = I \alpha$$

$$\tau = \left(\frac{1}{2} (3 \text{ kg}) (0.3 \text{ m})^2 \right) (9.12 \frac{\text{rad}}{\text{s}^2})$$

$$\tau = 1.23 \text{ N}\cdot\text{m}$$

$$\tau_{\text{fr}} = (F_{\text{fr}})(r) \quad \downarrow \text{r of hub}$$
$$(1.23 \text{ N}\cdot\text{m}) = (F_{\text{fr}})(0.1 \text{ m})$$

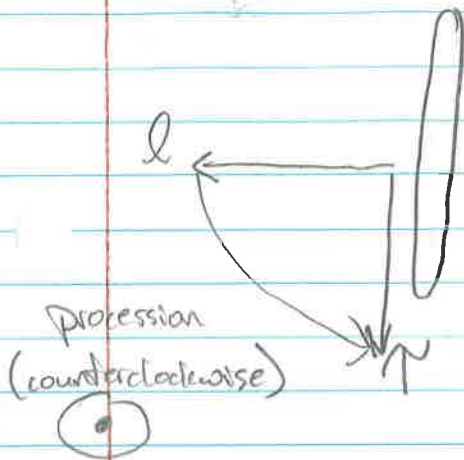
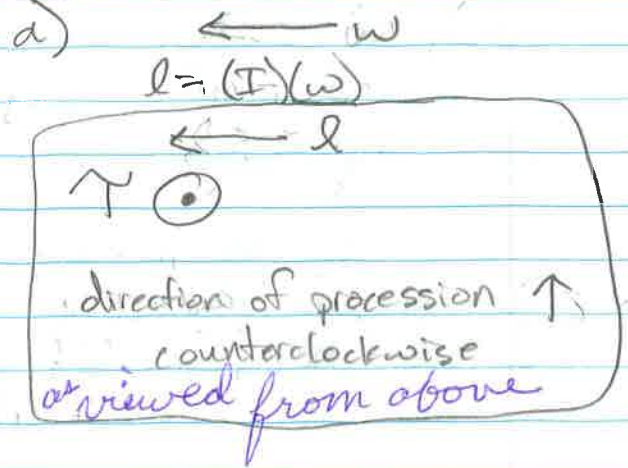
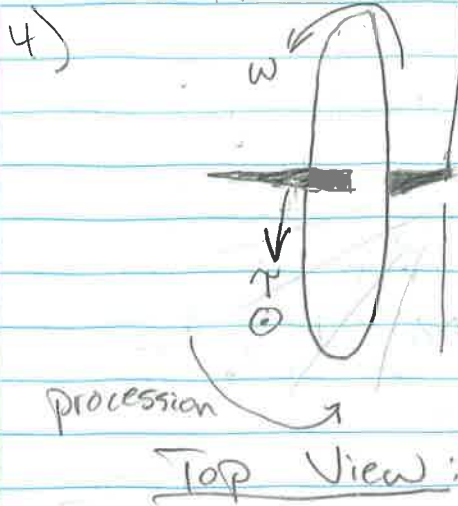
$$F_{\text{fr}} = 12.3 \text{ N}$$

$$e) \sum F_x = ma = F_{\text{gx}} - F_{\text{fr}} \quad \downarrow$$
$$(\sin 30)(3 \text{ kg})(10 \frac{\text{m}}{\text{s}^2}) - (12.3 \text{ N}) = (3 \text{ kg})(a)$$

$$a = 0.9 \frac{\text{m}}{\text{s}^2}$$

✓
yes they
are the
same!

Problem Set #9



b) If you initially spin the wheel the other direction, it will precess the other way. Precession is the resultant vector of l and T , and if the direction of l changes, then the resultant precession vector will go in the other direction.

c) It will precess ^{slower} less with a larger "w", because if "w" is larger, then "l" is larger, and the T vector will affect the larger "l" vector less, causing it to precess less. slower

d) $T = (F_g)(\Delta x)$. If " Δx " or the distance between the finger and the wheel decreases, then T decreases, causing the wheel to precess less. slower

$$e) \quad l = I\omega$$

$$I_0 = mr^2, \quad I_f = \frac{1}{2}mr^2$$

$$I_f < I_0$$

If the moment of inertia decreases as shown above, the "l" or angular momentum will decrease. If the "l" vector decreases, then the Torque vector will have a greater effect on it, causing the wheel to precess more.

Sooner



a) $PE_i = (70 \text{ kg})(10 \text{ m/s}^2)(40 \text{ m}) = 28000 \text{ J}$

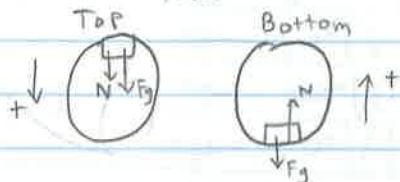
$PE_{\text{Top of Loop}} = (70 \text{ kg})(10 \text{ m/s}^2)(20 \text{ m}) = 14000 \text{ J}$

$28000 \text{ J} = \frac{1}{2}mv^2, V_{\text{bottom}} = 28.28 \text{ m/s}$

$14000 \text{ J} = \frac{1}{2}mv^2, V_{\text{top}} = 20 \text{ m/s}$

$a_{\text{bottom}} = \frac{(28.28 \text{ m/s})^2}{10 \text{ m}} = 80 \text{ m/s}^2$

$a_{\text{top}} = \frac{(20 \text{ m/s})^2}{10 \text{ m}} = 40 \text{ m/s}^2$



$\Sigma F_c = ma_c$

$N + F_g = ma_c$

$N = ma_c - F_g$

$N = (70 \text{ kg})(40 \text{ m/s}^2) - (70 \text{ kg})(10 \text{ m/s}^2) = \boxed{2100 \text{ N}}$

$\Sigma F_c = ma_c$

$N - F_g = ma_c$

$N = ma_c + F_g$

$N = (70 \text{ kg})(80 \text{ m/s}^2) + (70 \text{ kg})(10 \text{ m/s}^2) = \boxed{6300 \text{ N}}$

→ As you round the bottom of the loop, you feel more force pushing down on you. This is not a good ride for a pregnant woman!

b) If you start at the height as the top of the loop, you won't have enough velocity to make it around the top of the loop, because if energy is conserved, then KE will be 0 as you approach the top of the loop.

$$c) PE_i = PE_f + KE_f \quad \Sigma F = ma_c$$

$$mgh = mg(20m) + \frac{1}{2}mv^2 \quad F_g < ma_c$$

$$gh = g(20m) + \frac{1}{2}v^2 \quad mg < ma_c$$

↓

$$(10 \text{ m/s}^2)h = (10 \text{ m/s}^2)(20m) + \frac{1}{2}(10.01 \text{ m/s})^2 \quad \frac{v^2}{r} > g$$

$$\boxed{h > 25 \text{ m}}$$

$$v > \sqrt{gr}$$

$$v > 10 \text{ m/s}$$

$$d) KE = \frac{1}{2}I\omega^2 + \frac{1}{2}mv^2$$

$$= \frac{1}{2}I\frac{v^2}{r^2} + \frac{1}{2}mv^2$$

$$= \frac{1}{2} \cdot \frac{2}{3}m r^2 \frac{v^2}{r^2} + \frac{1}{2}mv^2$$

$$= \frac{2}{6}mv^2 + \frac{1}{2}mv^2$$

$$= \frac{5}{6}mv^2$$

PE = 28000 J at top

$$\text{So, } KE_{\text{bottom}} = 28000 \text{ J} = \frac{5}{6}(70 \text{ kg})v^2, \quad v = 21.9 \text{ m/s}, \quad a_c = 48 \text{ m/s}^2$$

$$KE_{\text{top}} = 14000 \text{ J} = \frac{5}{6}(70 \text{ kg})v^2, \quad v = 15.49 \text{ m/s}, \quad a_c = 24 \text{ m/s}^2$$



Bottom

$$\Sigma F = ma_c$$

$$-F_g + F_N = (70 \text{ kg})(48 \text{ m/s}^2)$$

$$F_N = 3360 \text{ N} + 700 \text{ N} = \boxed{4060 \text{ N}}$$

Top

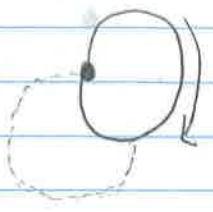


$$\Sigma F = ma_c$$

$$F_g + F_N = ma_c = (70 \text{ kg})(24 \text{ m/s}^2)$$

$$F_N = 1680 \text{ N} - 700 \text{ N} = \boxed{980 \text{ N}}$$

6



a. We can use energy to solve this. Knowing energy is conserved.

PE is converted all into KE. Let $h=r$, so:

$$mgr = \frac{1}{2} I \omega^2 + \frac{1}{2} m v^2$$

$$mgr = \frac{1}{2} I \omega^2 + \frac{1}{2} m r^2 \omega^2$$

$$mgr = \frac{1}{2} \omega^2 [I + m r^2]$$

$$mgr = \frac{1}{2} \omega^2 \left[\frac{1}{2} m r^2 + m r^2 \right]$$

$$mgr = \left(\frac{1}{2} \omega^2 \right) \left(\frac{3}{2} m r^2 \right)$$

$$g = \frac{3}{2} \cdot \frac{1}{2} \omega^2 r$$

$$\omega = \sqrt{\frac{4g}{3r}} = \boxed{\frac{2\sqrt{3g}}{3r} \frac{\text{rad}}{\text{Sec.}}}$$

b. $I = \frac{1}{2} m r^2$, $L = I \omega$, so $L = \frac{1}{2} m r^2 \left(\frac{2\sqrt{3g}}{3r} \right) = \frac{1}{3} \frac{m r^2 \sqrt{3g}}{r}$

$$L = \boxed{\frac{m r \sqrt{3g}}{3}}$$

c.



→ dynamics, because we know there is a centripetal acceleration from the nail, as well as a force of gravity and a force from the nail.

$$\sum F_c = m a_c$$

$$= \frac{m \left(\frac{4g}{3} \right) r}{r}$$

$$= mg \left(\frac{4}{3} \right)$$

$$F_{\text{nail}} = m a_c + F_g$$

$$= m \omega^2 r + F_g$$

$$= m \left(\frac{4}{3} g \right) + mg$$

$$F_{\text{nail}} = \boxed{\frac{1}{3} mg}$$

$$\rightarrow \underline{\underline{2 \frac{1}{3} (mg)}}$$