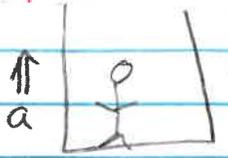


## Test Corrections

#1

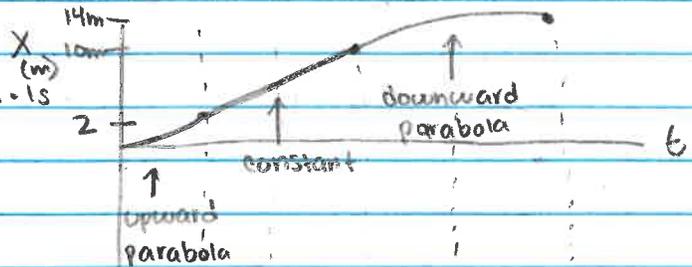
\* I am choosing a kinematics lens because we are looking at each component as an explicit function of time



$$t = 1s \rightarrow X = v_a \Delta t \quad v_a = \frac{v_f - v_i}{2} \quad v_a = 2 \text{ m/s} \cdot 1s$$

$$t = 2-3s \rightarrow X = 4 \text{ m/s} \cdot 2s \quad \Delta X = 8m$$

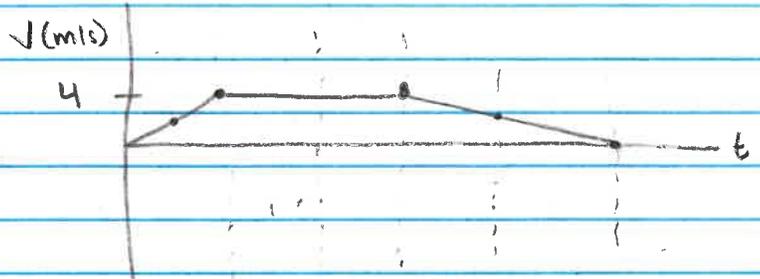
$$t = 4-5s \rightarrow X = 2 \text{ m/s} \cdot 2s \quad \Delta X = 4m$$



$$t = 1s \rightarrow v = 0 \text{ m/s to } 4 \text{ m/s}$$

$$t = 2-3s \rightarrow v = 4 \text{ m/s}$$

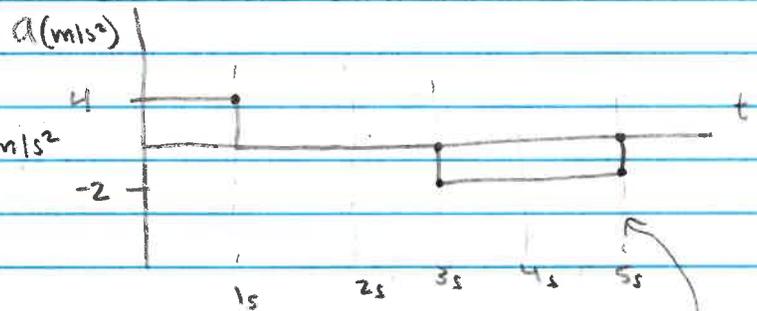
$$t = 4-5s \rightarrow v = 4 \text{ m/s to } 0 \text{ m/s}$$



$$t = 1s \rightarrow a = 4 \text{ m/s}^2$$

$$t = 2-3s \rightarrow a = 0 \text{ m/s}^2$$

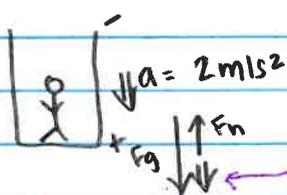
$$t = 4-5s \rightarrow a = -2 \text{ m/s}^2 \quad a = \frac{-4 \text{ m/s}}{2s} = -2 \text{ m/s}^2$$



A+

#2

\* I am choosing a dynamics lens because the deceleration of your body is caused by the normal force being less than gravity.



$$m = 100 \text{ kg} \quad \Sigma F = F_n + F_g \quad t = 3.5s \rightarrow a = -2 \text{ m/s}^2$$

$$\Sigma F = 100 \text{ kg} (2 \text{ m/s}^2)$$

\* From previous problem

$$\Sigma F = 200 \text{ N}$$

$$F_g = mg \quad F_g = 100 \text{ kg} (10 \text{ m/s}^2)$$

$$F_g = 1000 \text{ N}$$

$$F_n = \Sigma F - F_g \quad F_n = 200 \text{ N} - 1000 \text{ N}$$

$$F_n = -800 \text{ N}$$

$$F_n = 800 \text{ N Upwards}$$

$$m = \frac{F_n}{g} \quad m = \frac{800 \text{ N}}{10 \text{ m/s}^2}$$

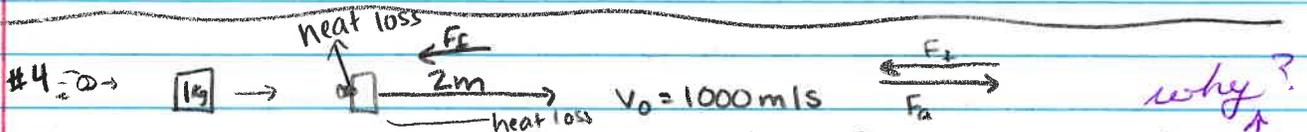
A

$$m = 80 \text{ kg} \leftarrow \text{Scale reads}$$

#3

\* I am going to use the energy lens because power is the rate of change of energy or work.  $m_1 = 100\text{kg}$   $m_2 = 900\text{kg}$

$E_{k1} + W = E_{kf} + E_{fg}$  @  $t=0\text{s}$   $v=0\text{m/s}$   $E_{k1} = 0\text{J}$   
 @  $t=2\text{s}$   $v=4\text{m/s}$   
 $W = E_{kf} + E_{fg}$   $E_{kf} = \frac{1}{2}m(v_f)^2$   $E_{fg} = mgh$   
 $E_{kf} = \frac{1}{2}(1000\text{kg})(4\text{m/s})^2$   $E_{fg} = 1000\text{kg}(10\text{m/s}^2)(6\text{m})$   
 $E_{kf} = 8000\text{J}$   $E_{fg} = 60,000\text{J}$   
 $W = 68,000\text{J}$   $P = \frac{W}{\Delta t}$   
 $P = \frac{68,000\text{J}}{2\text{s}}$   $P = 34,000\text{W}$   $\rightarrow P = 46\text{Hp}$



\* I am going to use a momentum lens first in order to find the final velocity because momentum is conserved within the system. I will then use an energy lens to find the amount of work done which will give me force needed to use a dynamics lens in order to find  $\mu$ .

$E_{k1} \rightarrow E_{k2} + E_{k3} - W_f$   $m_1 v_1 = m_{1+2} v_f$   $E_{k1} = \frac{1}{2}(1.005\text{kg})(1000\text{m/s})^2$   
 $1.005\text{kg}(1000\text{m/s}) = 1\text{kg}(v_f)$   $E_{k1} = 2,500\text{J}$   
 $E_{kf} = \frac{1}{2}(1.005\text{kg})(5\text{m/s})^2$   $5\text{kgm/s} = 1.005\text{kg}(v_f)$   
 $E_{kf} = 12.6\text{J}$   $v_f = 5\text{m/s}$   $N = mg$   $N = 1.005\text{kg}(10\text{m/s}^2)$   
 $N = 10.05\text{N}$

$F_f$  is equal & opposite to force applied.  $F_f = \mu N$

$E_{kf} = W_f$   $W_f = F_f \Delta x$   $F_f = \frac{12.6\text{J}}{2\text{m}}$   $F_f = 6.3\text{N}$   $\mu = \frac{F_f}{N}$   $\mu = \frac{6.3\text{N}}{10.05\text{N}}$   
 $F_f = \frac{W_f}{\Delta x}$   $\mu = 0.63$

Cinematics  $\rightarrow$

$v_a = \frac{5\text{m/s} - 0\text{m/s}}{2} = 2.5\text{m/s}$   $t = \frac{\Delta x}{v}$   $t = \frac{2\text{m}}{2.5\text{m/s}}$   $t = 0.8\text{s}$   
 $a = \frac{5\text{m/s}}{0.8\text{s}}$   $a = 6.25\text{m/s}^2$

Dynamics  $\rightarrow$

$F = ma$   $F = 1.005\text{kg}(6.25\text{m/s}^2)$   $F_f = 6.3\text{N}$   $\mu = \frac{F_f}{N}$   $\mu = \frac{6.3\text{N}}{10.05\text{N}}$   $\mu = 0.63$

using E  
using  
dynamics +  
Kinematics